

Aufgabe 2.1

a) $x_S(t) = v_S t + r$, $\omega_2 = \frac{v_S}{r}$

b) $\vec{v}_A = \vec{v}_S + \vec{\omega}_1 \times \vec{r}_{SA}$

$$= \begin{pmatrix} v_S \\ 0 \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ 0 \\ \dot{\varphi} \end{pmatrix} \times \begin{pmatrix} -a \sin(\varphi) \\ a \cos(\varphi) \\ 0 \end{pmatrix}$$

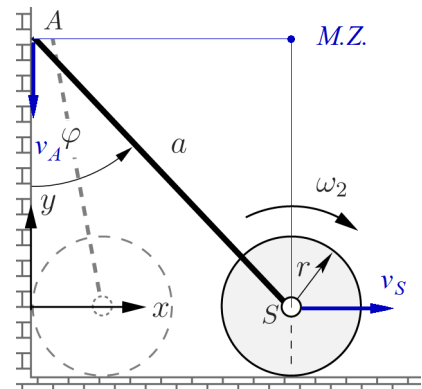
$$= \begin{pmatrix} v_S - a \dot{\varphi} \cos(\varphi) \\ -a \dot{\varphi} \sin(\varphi) \\ 0 \end{pmatrix} \stackrel{!}{=} \begin{pmatrix} 0 \\ -v_A \\ 0 \end{pmatrix}$$

$$\Rightarrow v_S - a \dot{\varphi} \cos(\varphi) = 0 \Rightarrow \dot{\varphi} = \frac{v_S}{a \cos(\varphi)}$$

c) $x_S(T) = v_S T + r \stackrel{!}{=} a \Rightarrow T = \frac{a - r}{v_S}$

$$\varphi = 30^\circ \Rightarrow \cos(30^\circ) = \frac{\sqrt{3}}{2} \Rightarrow \dot{\varphi} = \frac{2v_S}{\sqrt{3}a}$$

$$\varphi = 90^\circ \Rightarrow \cos(90^\circ) = 0 \Rightarrow \dot{\varphi} = \infty$$



Aufgabe 2.2

a) $\ddot{\varphi}(t) = \varepsilon$, $\dot{\varphi}(0) = \frac{v_0}{r}$, $\varphi(0) = 0$

$$\Rightarrow \dot{\varphi}(t) = \varepsilon t + \frac{v_0}{r}, \quad \varphi(t) = \frac{1}{2} \varepsilon t^2 + \frac{v_0}{r} t$$

$$\varphi(t_1) = \frac{1}{2} \varepsilon t_1^2 + \frac{v_0}{r} t_1 \stackrel{!}{=} \pi + \alpha$$

$$\Rightarrow t_1^2 + \frac{2v_0}{\varepsilon r} t_1 - \frac{2(\pi + \alpha)}{\varepsilon} = 0 \quad \Rightarrow \quad t_1 = -\frac{v_0}{\varepsilon r} + \sqrt{\left(\frac{v_0}{\varepsilon r}\right)^2 + \frac{2(\pi + \alpha)}{\varepsilon}}$$

$$\dot{\varphi}(t_1) = \varepsilon t_1 + \frac{v_0}{r} = \varepsilon \left(-\frac{v_0}{\varepsilon r} + \sqrt{\left(\frac{v_0}{\varepsilon r}\right)^2 + \frac{2(\pi + \alpha)}{\varepsilon}} \right) + \frac{v_0}{r} \stackrel{!}{=} \dot{\varphi}(t_1) = \frac{v_1}{r}$$

$$\Rightarrow \varepsilon \sqrt{\left(\frac{v_0}{\varepsilon r}\right)^2 + \frac{2(\pi + \alpha)}{\varepsilon}} = \frac{v_1}{r} \quad \Rightarrow \quad \left(\frac{v_0}{\varepsilon r}\right)^2 + \frac{2(\pi + \alpha)}{\varepsilon} = \left(\frac{v_1}{\varepsilon r}\right)^2$$

$$\Rightarrow v_0 = \sqrt{v_1^2 - 2\varepsilon r^2(\pi + \alpha)} = \sqrt{625 \text{ m}^2 \text{ s}^{-2} - 2 \cdot \frac{75}{7\pi} \text{ s}^{-2} \cdot 9 \text{ m}^2 \cdot \frac{7\pi}{6}} = 20 \text{ m s}^{-1}$$

$$a_{N1} = \frac{v_1^2}{r} \approx 208,3 \text{ m s}^{-2}$$

b) $x(t) = v_1 \cos(\alpha) t$, $y(t) = -\frac{1}{2} g t^2 + v_1 \sin(\alpha) t$

$$x(t_2) = v_1 \cos(\alpha) t_2 \stackrel{!}{=} l \quad \Rightarrow \quad t_2 = \frac{l}{v_1 \cos(\alpha)} \approx 1,85 \text{ s}$$

$$y_2 = y(t_2) = -\frac{1}{2} g t_2^2 + v_1 \sin(\alpha) t_2 \approx 6,03 \text{ m}$$

$$h_2 = y_2 + r - r \cos(\alpha) = y_2 + r(1 - \cos(\alpha)) \approx 6,43 \text{ m}$$

c) $\dot{x}(t_2) = v_1 \cos(\alpha) \approx 21,65 \text{ m s}^{-1}$, $\dot{y}(t_2) = -g t_2 + v_1 \sin(\alpha) \approx -5,97 \text{ m s}^{-1}$

$$v_2 = \sqrt{(\dot{x}(t_2))^2 + (\dot{y}(t_2))^2} \approx 22,45 \text{ m s}^{-1}, \quad \beta = \tan^{-1} \left(\frac{\dot{x}(t_2)}{|\dot{y}(t_2)|} \right) \approx 74,6^\circ$$